RT303 Rotary Temperature Transmitter (850-385)

The RT303 rotary temperature transmitter is a digital system designed to accurately transmit temperature data from RTD sensors embedded in a heated godet roll shell. The system consists of three components: The RT303R rotary assembly, the RT300S stationary assembly and the RT303C controller interface assembly



Installation

 Slide the RT303R rotary assembly onto shaft with steel base toward motor. Tighten the (2) 1/4 20 compression screws (alternating from one screw to the other) to lock assembly onto shaft.

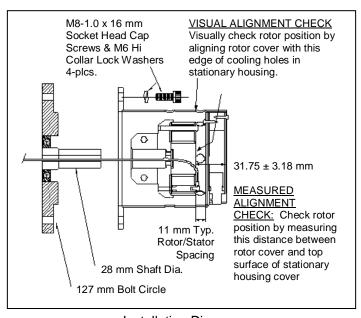
Note: The RT303R requires proper positioning on the shaft; see Step 5 below for details.

- 2. Secure RTD leads with the 4-40 x 1/4" socket head cap screws provided.
- IMPORTANT! Pull excess RTD leads towards the front of the godet roll to be stored under the godet cover. This prevents lead wires from rubbing against inside cover of RT300S stationary housing during rotation.
- Carefully position the RT300S stationary housing over shaft-mounted RT303R transmitter and mount it to the motor.
- 5. **IMPORTANT!** Refer to the diagram below to verify correct axial spacing between rotor and stator using either of the following methods:

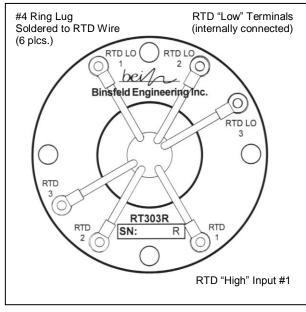
<u>Visual Alignment</u>: sight the outer face of the rotor through the side ventilation holes in the stator.

<u>Measured Alignment</u>: insert a steel scale through the ventilation slots in the cover of the stator and measure 1-1/4 ± 1/8 inches from the stator (RT300S) cover to the outer face of the rotor.

- DIN rail (35mm) mount the RT303C current controller interface at a convenient location. CAUTION: To promote airflow and prevent overheating, the RT303C must have at least 1 inch clearance above and below the enclosure.
- Connect one end of the provided coax cable to the BNC plug on the RT300S stationary housing and the other end to the BNC plug on the RT303C.
- Connect a power source to the proper terminals indicated on the RT303C. Acceptable power is 22-35VDC or 17-27VAC. CAUTION: Power source must be isolated from current output.
- Connect the 4-20mA current loop (from the customer's process controller) to the current source terminals indicated on the RT303C.
- 10. Allow a 30 second start up.



Installation Diagram



Rotor/RTD Wiring Diagram

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Troubleshooting

In normal operating mode the Power status light, the Data status light and the CH status light are all on solid. In error mode, one or more of the LED's on the RT303C Controller Interface will flash and a high temperature signal (approximately 24 mA) will be output. Refer to the table below when troubleshooting an error mode event.

| (approximately 24 mA) will be output. Refer to | | A) wiii be output. Refer to the tab |
|--|---|--|
| | Power Status On solid Flash fast (5Hz) | <u>Condition</u> Stator and rotary power in spec Rotary power out of spec |
| | Flash slow (2Hz) Off | Stationary power out of spec System not powered |
| | 10 sec on/1 sec off [Data light off, RTD light(s) blinking] | Insufficient rotary power or data not received (Rotor Reset mode) |
| | <u>Data Status</u> On solid Flickering | <u>Condition</u> Digital transmission is error-free Intermittent transmission errors |
| | 0" | 5 |

Off Data not received

Ch 1 Status Condition No errors detected On solid Flash fast (5Hz) Rotary side error:

RTD out of range (including

open or shorted)

Open circuit in 4-20mA loop Flash slow (2Hz)

continuity of current loop

Corrective Action

Check rotor/stator spacing, and coaxial connections Check power source Check power source, and power connections

Check rotor/stator spacing, and coaxial connections

Corrective Action

Check rotor/stator spacing,

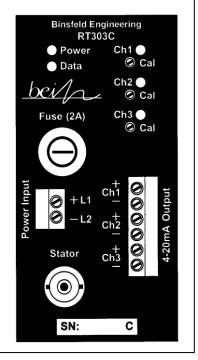
coax connections

Check rotor/stator spacing, and coaxial connections

Corrective Action

Check RTD, connections

Check connections and



Status Indicators & I/O Diagram

If the status lights do not agree with conditions listed above, remove power to the RT303C for 5 seconds, and then restore power (to reset the digital circuitry). Go to http://www.binsfeld.com/temptrak/rt300/ for more trouble shooting aids.

Specifications

Rotor: Number of sensors

Sensor connection: #4-40 screw terminals with socket-head cap screws PT100 RTD (100 Ω at 0° C, α =.00385, two wire) Input sensor type:

0 - 300° C Sensor range: 10.000 RPM Speed:

Stator: Connector: Coaxial interconnect (BNC)

Controller Output connection: Quick connect screw terminal block. Interface: Output signal: 4-20 mA (Linear with 0 - 300° C)

Power input: 22-35 VDC or 17-27 VAC; 2A max, 0.5A nominal

Max load resistance 400 Ω

General: Accuracy (typical error): ±0.30% span over operating temperature range

Operating temperature: 0 – 100° C

Humidity: 0-90% RH, non-condensing

This document is subject to change without prior notification.

Warrantv

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