# RT301(2) Rotary Temperature Transmitter (850-375)

The RT301(2) dual output rotary temperature transmitter is a digital system designed to accurately transmit temperature data from an RTD sensor embedded in the heated godet roll shell. The system consists of three components: The RT301R rotary assembly, the RT300S stationary assembly and the RT301(2)C controller interface assembly.



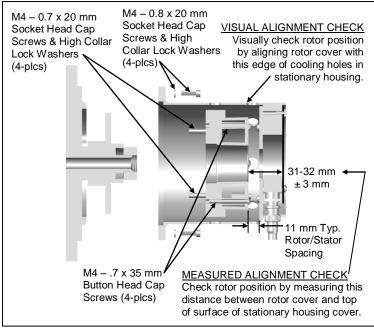
### Installation

- Remove existing stationary components and adapter ring from motor mounting face. Remove existing rotating equipment from motor shaft. Leave the tapered shaft mounting plate and nut attached to the tapered shaft.
- 2. Attach the RT301R rotary base onto the original mounting plate with (4) M4-.7 x 20mm socket head cap screws. Attach the RT301R rotary assembly onto the rotating base with (4) M4-.7 x 35mm button head cap screws. BEI recommends using LocTite 222MS (or equivalent) thread locker on all of the above mentioned screw threads.
- Review the Rotor/RTD Connection Diagram for wiring the RTD connections onto the RT301R rotary assembly. Secure leads with the M3-0.5 x 6mm socket head cap screws provided.
- 4. IMPORTANT! Pull excess RTD leads towards the front of the godet roll to be stored under the godet cover. This prevents lead wires from rubbing against the inside cover of RT300S stationary housing during rotation.
- Carefully position the RT300S stationary housing over shaftmounted RT301R transmitter and mount it to the motor face using (4) M5-0.8 x 20mm long socket head cap screws with high collar lock washers provided.
- 6. **IMPORTANT!** Refer to the <u>Installation Diagram</u> above to verify correct axial spacing between rotor and stator using either of the following methods:

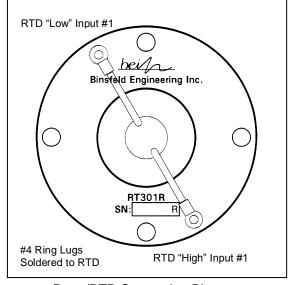
<u>Visual Alignment</u>: sight the outer face of the rotor through the side ventilation holes in the stator.

<u>Measured Alignment</u>: insert a steel scale through the ventilation slots in the cover of the stator and measure 31-32 mm ±3 mm from the stator (RT300S) cover to the outer face of the rotor.

- 7. DIN rail (35mm) mount the RT301(2)C controller interface at a convenient location. CAUTION: To promote airflow and prevent overheating, the RT301(2)C must have at least 25.4 mm clearance above and below the enclosure.
- Connect one end of the provided coax cable to the BNC plug on the RT300S stator housing and the other end to the plug on the RT301(2)C.
- 9. Connect a 24VDC power source to the proper terminals indicated on the RT301(2)C.



Installation Diagram



Rotor/RTD Connection Diagram

### CAUTION: Power source must be isolated from current and voltage outputs.

- 10. Connect the voltage input leads (from the customer's process controller) to the voltage (Vout) terminals indicated on the RT301(2)C. (Alternatively, connect the <u>current</u> input leads from the customer's process controller to the <u>current</u> lout terminals on the RT301(2)C.)
- 11. Insert a jumper wire across the current loop output (lout) terminals when the current output signal is not used.
- 12. Allow a 30 second start up.

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### **Troubleshooting**

In normal operating mode the Power status light, the Data status light and the CH status light are all on solid. In error mode, one or more of the LED's on the RT301(2)C Controller Interface will flash and a high temperature signal (approximately 24 mA) will be output. Refer to the table below when troubleshooting an error mode event.

•	<u> </u>
Power Status On solid Flash fast (5Hz)	Condition Stator and rotary power in spec Rotary power out of spec
Flash slow (2Hz) Off	Stationary power out of spec System not powered
10 sec on/1 sec off	Insufficient rotary power or data

lata not received (Rotor Reset mode)

[Data light off, RTD light(s) blinking] **Data Status** 

Condition Digital transmission is error-free On solid Flickering Intermittent transmission errors

Off Data not received

Ch 1 Status Condition No errors detected On solid Flash fast (5Hz) Rotary side error:

RTD out of range (including

open or shorted)

Open circuit in 4-20mA loop Flash slow (2Hz)

continuity of current loop

**Corrective Action** 

Check rotor/stator spacing, and coaxial connections Check power source Check power source, and power connections Check rotor/stator spacing,

and coax connections

**Corrective Action** 

Check rotor/stator spacing,

coax connections Check rotor/stator spacing, and coaxial connections

**Corrective Action** 

Check RTD, connections

Check connections and

Binsfeld Engineering RT301(2)C Ch1 O I Cal V Cal Fuse (2A) С

Status Indicators & I/O Diagram

If the status lights do not agree with conditions listed above, remove power to the RT301(2)C for 5 seconds, and then restore power (to reset the digital circuitry). Go to http://www.binsfeld.com/temptrak/rt300/ for more trouble shooting aids.

### **Specifications**

Rotor: Number of sensors

> Sensor connection: M3 screw terminals with socket-head cap screws Input sensor type: PT100 RTD (100  $\Omega$  at 0° C,  $\alpha$ =.00385, two wire)

Sensor range:  $0 - 300^{\circ} C$ Speed: 10,000 RPM

Stator: Connector: Coaxial interconnect (BNC)

Controller Output connection: Quick connect screw terminal block.

Interface: Output signal: 4-20 mA or 0.0 - 3.0 VDC output (Linear with 0 - 300° C)

Power input: 24 VDC, 1 A max, 0.5 A nominal

Max load resistance 400 Ω

Accuracy (typical error): ±0.30% span over operating temperature range General:

Operating temperature: 0 - 100° C

0-90% RH, non-condensing Humidity:

This document is subject to change without prior notification.

### Warrantv

Binsfeld Engineering Inc. warrants this product to be free from defective materials and workmanship for a period of five years from the date of delivery to the original purchaser and that this product will conform to specifications and standards published by Binsfeld Engineering Inc. Upon evaluation by Binsfeld Engineering Inc., any product found to be defective will be replaced or repaired at the sole discretion of Binsfeld Engineering Inc. Our warranty is limited to the foregoing. Binsfeld Engineering Inc. disclaims any warranty of merchantability or fitness for intended purpose.