## RT302 Rotary Temperature Transmitter (850-370)

The RT302 rotary temperature transmitter is a digital system designed to accurately transmit temperature data from RTD sensors embedded in a heated godet roll shell. The system consists of three components: The RT302R rotary assembly, the RT300S stationary assembly, and the RT302C controller interface assembly.







#### Installation

 Slide the RT302R rotary assembly onto shaft with steel base toward motor. Tighten the (2) M6 compression screws (alternating from one screw to the other) to lock assembly onto shaft.

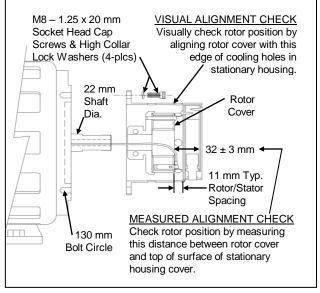
Note: The RT302R requires proper positioning on the shaft; see Step 5 below for details.

- 2. Secure RTD leads with the M3 socket head cap screws provided.
- IMPORTANT! Pull excess RTD leads towards the front of the godet roll to be stored under the godet cover. This prevents lead wires from rubbing against inside cover of RT300S stationary housing during rotation.
- Carefully position the RT300S stationary housing over shaftmounted RT302R transmitter and mount it to the motor.
- IMPORTANT! Refer to the Installation Diagram to verify correct axial spacing between rotor and stator using either of the following methods:

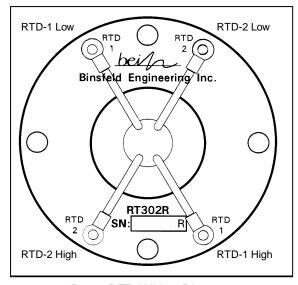
<u>Visual Alignment</u>: sight the outer face of the rotor through the side ventilation holes in the stator.

<u>Measured Alignment</u>: insert a steel scale through the ventilation slots in the cover of the stator and measure 1- $32 \pm 3$  mm from the stator (RT300S) cover to the outer face of the rotor.

- DIN rail (35mm) mount the RT302C current controller interface at a convenient location. CAUTION: To promote airflow and prevent overheating, the RT302C must have at least 25 mm clearance above and below the enclosure.
- 7. Connect one end of the provided coax cable to the BNC plug on the RT300S stationary housing and the other end to the BNC plug on the RT302C.
- Connect a power source to the proper terminals indicated on the RT302C. Acceptable power is 23-30 VDC or 18-23 VAC. CAUTION: Power source must be isolated from current output.
- Connect the 4-20mA current loop (from the customer's process controller) to the current source terminals indicated on the RT302C.
- 10. Allow 30 seconds for start up.



Installation Diagram



Rotor-RTD Wiring Diagram

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### **Troubleshooting**

In normal operating mode the Power status light, the Data status light and the Channel (Ch) status light are all on solid. In error mode, one or more of the lights on the RT302C Controller Interface will flash and a high temperature signal (approximately 24 mA) will be output. Refer to the table below when troubleshooting an error mode event.

Power StatusConditionOn solidStator & rotor power in specFlash fast (5Hz)Rotary power out of spec

Flash slow (2Hz) Stationary power out of spec Off System not powered

10 sec on/1 sec off Insufficient rotary power or data (Data light off, RTD not received (Rotor Reset mode) light(s) blinking)

Data Status Condition

On solid Digital transmission is error-free Flickering Intermittent transmission errors

Off Data not received

Ch 1 - 2 Status Condition

On solid No errors detected Flash fast (5Hz) Rotary side error:

RTD out of range (including

open or shorted)

Flash slow (2Hz) Open circuit in 4-20mA loop

continuity of current loop

#### **Corrective Action**

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Check rotor/stator spacing, and coaxial connections Check power source Check power source, and power connections Check rotor/stator spacing, and coaxial connections

#### **Corrective Action**

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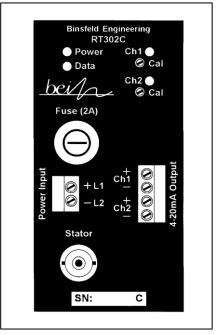
Check rotor/stator spacing, and coaxial connections Check rotor/stator spacing, and coaxial connections

#### **Corrective Action**

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Check RTD, connections

Check connections and



Status Indicators & I/O Diagram

If the status lights do not agree with conditions listed above, remove power to the RT302C for 5 seconds, and then restore power (to reset the digital circuitry). Go to <a href="http://www.binsfeld.com/temptrak/rt300/">http://www.binsfeld.com/temptrak/rt300/</a> for more trouble shooting aids.

### **Specifications**

Rotor: Number of sensors: 1 - 2

Sensor connection: M3-0.5 screw terminals with socket-head cap screws Input sensor type: PT100 RTD (100  $\Omega$  at 0°C,  $\alpha$  = .00385, two wire)

Sensor range:  $0 - 300^{\circ}$  C Speed: 10,000 RPM

Stator: Connector: Coaxial interconnect (BNC)

Controller Output connection: Quick connect screw terminal block. Interface: Output signal: 4-20 mA (Linear with 0° to 300° C)

Power input: 23-30 VDC or 18-23 VAC, 2 A max, 1 A nominal

Max load resistance 400  $\Omega$ 

General: Accuracy (typical error): ±0.30% span over operating temperature range

Operating temperature: 0 – 100° C

Humidity: 0-90% RH, non-condensing

This document is subject to change without prior notification.

#### Warranty

Binsfeld Engineering Inc. warrants this product to be free from defects for a period of five years from the date of delivery to the original purchaser and that its products will conform to specifications and standards published by Binsfeld Engineering Inc. Upon evaluation by Binsfeld Engineering Inc., any product found to be defective will be replaced or repaired at the sole discretion of Binsfeld Engineering Inc. Our warranty is limited to the foregoing. Binsfeld Engineering Inc. disclaims any warranty of merchantability or fitness for intended purpose.