

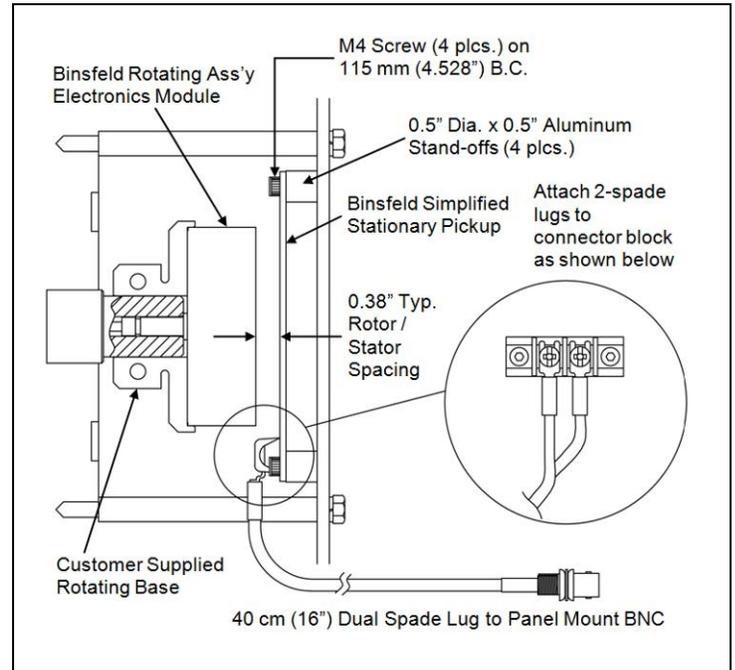
# RT304 Rotary Temperature Transmitter (850-356)

The RT304 rotary temperature transmitter is a digital system designed to accurately transmit temperature data from RTD sensors embedded in a heated godet roll shell. The system consists of three components: The **RT304R** rotary assembly, the **RT300S** stationary assembly, and the **RT304C** controller interface assembly.

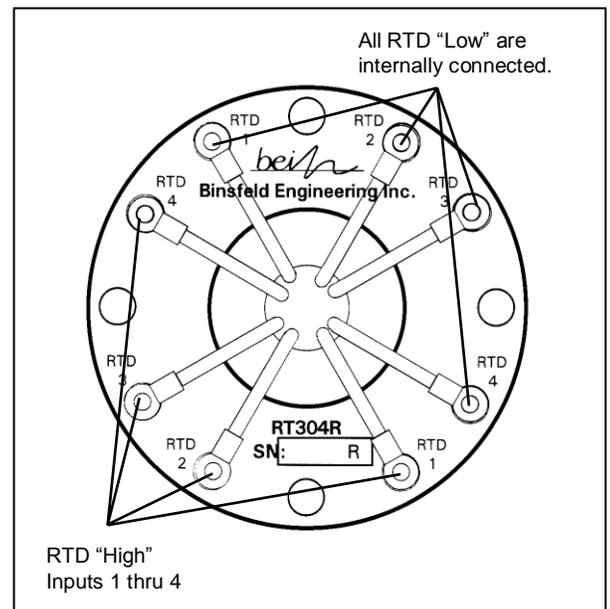


## Installation

- Secure the RT304R transmitter module (provided) to the rotating base using button head cap screws with thread-locking adhesive (Loctite 222MS or equivalent).
- Slide the RT304R rotary assembly onto shaft with steel base toward motor. Secure the base to the shaft by tightening the compression screws (alternating from one screw to the other).  
**Note:** The RT304R requires proper positioning on the shaft; see Step 7 for details.
- Review the drawing below for wiring the RTD connections onto the RT304R rotary assembly. Secure leads with the M3 socket head cap screws provided.
- IMPORTANT!** Pull excess RTD leads towards the front of the godet roll to be stored under the godet cover. This prevents lead wires from rubbing against the RT300S stationary board during rotation.
- Secure the RT300S stationary assembly to the cross brace using M4 bolts (provided) and 4 standoffs (provided) with thread-locking adhesive (Loctite 222MS or equivalent).
- Insert the 40 cm coax adapter cable, spade lugs first, into the motor backplane and thread the BNC connector in place. Install the lockwasher and jam nut on the back of the connector. Feed the spade lug end of the cable through the 6 mm hole in the fan housing and connect the spade lugs to the terminal strip on the RT300S stationary assembly (polarity not important).
- Reinstall the cross brace. Verify that the rotor to stator spacing is approximately 10 mm (0.38 inches).
- DIN rail (35mm) mount the RT304C controller interface at a convenient location. **CAUTION: To promote airflow and prevent overheating, the RT304C must have at least 25 mm clearance above and below the enclosure.**
- Connect one end of the interconnect cable to the BNC bulkhead connector on the adapter cable (installed in motor backplane) and the other end to the BNC plug on the RT304C.
- Connect a power source to the proper terminals indicated on the RT304C. Acceptable power is 22-35VDC or 17-27VAC. **CAUTION: Power source must be isolated from current output.**
- Connect the 4-20 mA current loops (from the customer's process controller) to the current source terminals indicated on the RT304C.
- Allow a 30 second start up.



Installation Diagram



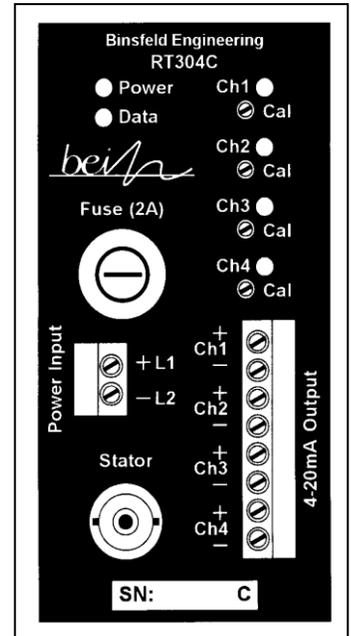
Rotor/RTD Connections

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## Troubleshooting

In normal operating mode the Power status light, the Data status light and the Ch(annel) status light are all on solid. In error mode, one or more lights on the RT304C Controller Interface will flash and a high temperature signal (approximately 24 mA) will be present at the output. Refer to the table below when troubleshooting an error mode event.

<u>Power Status</u>	<u>Condition</u>	<u>Corrective Action</u>
On solid	Stator and rotary power in spec	---
Flash fast (5Hz)	Rotary power out of spec	Check rotor/stator spacing, and coaxial connections
Flash slow (2Hz)	Stationary power out of spec	Check power source
Off	System not powered	Check power source, and power connections
10 sec on/1 sec off [Data light off, RTD light(s) blinking]	Insufficient rotary power or data not received (Rotor Reset mode)	Check rotor/stator spacing, and coaxial connections
<u>Data Status</u>	<u>Condition</u>	<u>Corrective Action</u>
On solid	Digital transmission is error-free	---
Flickering	Intermittent transmission errors	Check rotor/stator spacing, coax connections
Off	Data not received	Check rotor/stator spacing, and coaxial connections
<u>Ch 1 Status</u>	<u>Condition</u>	<u>Corrective Action</u>
On solid	No errors detected	---
Flash fast (5Hz)	Rotary side error: RTD out of range (including open or shorted)	Check RTD's & connections
Flash slow (2Hz)	Open circuit in 4-20mA loop	Check connections and continuity of current loop



Status Indicators & I/O Diagram

If the status lights do not agree with conditions listed above, remove power to the RT304C for 5 seconds, and then restore power (to reset the digital circuitry). Go to <http://www.binsfeld.com/temptrak/rt300/> for more troubleshooting aids.

## Specifications

Rotor:	Number of sensors	1-4
	Sensor connection:	M3 screw terminals with socket-head cap screws
	Input sensor type:	PT100 RTD (100 $\Omega$ at 0° C, $\alpha=$ .00385, two wire)
	Sensor range:	0 – 300° C
	Speed:	10,000 RPM
Stator:	Connector:	Coaxial interconnect (BNC)
Controller Interface:	Output connection:	Quick connect screw terminal block.
	Output signal:	4-20 mA (Linear with 0 - 300° C)
	Power input:	22-35 VDC or 17-27 VAC; 2A max, 0.5A nominal
	Max load resistance	400 $\Omega$
General:	Accuracy (typical error):	$\pm$ 0.30% span over operating temperature range
	Operating temperature:	0 – 100°
	Humidity:	0 – 90% RH, non-condensing

This document is subject to change without prior notification.

## Warranty

Binsfeld Engineering Inc. warrants this product to be free from defective materials and workmanship for a period of five years from the date of delivery to the original purchaser and that this product will conform to specifications and standards published by Binsfeld Engineering Inc. Upon evaluation by Binsfeld Engineering Inc., any product found to be defective will be replaced or repaired at the sole discretion of Binsfeld Engineering Inc. Our warranty is limited to the foregoing. Binsfeld Engineering Inc. disclaims any warranty of merchantability or fitness for intended purpose.