# RT304 Rotary Temperature Transmitter (850-317)

The RT304 rotary temperature transmitter is a digital system designed to accurately transmit temperature data from RTD sensors embedded in the heated godet roll shell. The system consists of three components: The RT304R rotary assembly, the RT300S stationary assembly and the RT304C controller interface assembly.



#### Installation

 Slide the RT304R rotary assembly onto shaft with steel base toward motor. Tighten the (2) 1/4 - 20 compression screws (alternating from one screw to the other) to lock assembly onto shaft.

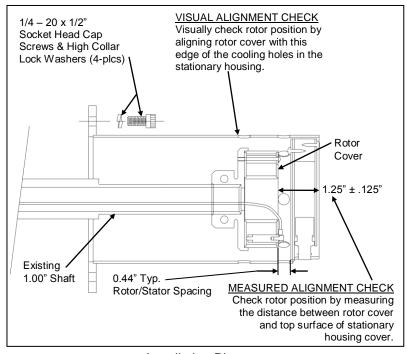
Note: The RT304R requires proper position on the shaft; see Step 5 below for details.

- Review the drawing below for wiring the RTD connections onto the RT304R rotary assembly.
   Secure leads with the 4-40 x 1/4" socket head cap screws provided.
- IMPORTANT! Pull excess RTD leads towards the front of the godet roll to be stored under the godet cover. This prevents leads from rubbing against inside cover of RT300S stationary housing during rotation.
- Carefully position the RT300S stationary housing over shaft-mounted RT304R transmitter and mount it to the motor using (4) ½-20 x ½ inch long socket head cap screws and lock washers provided.
- 5. **IMPORTANT!** Refer to the <u>Installation Diagram</u> to verify correct axial spacing between rotor and stator using either of the following methods:

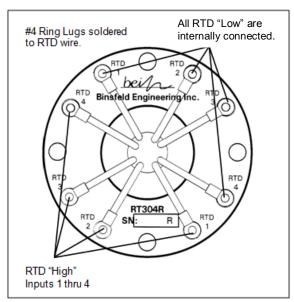
<u>Visual Alignment</u>: sight the outer face of the rotor through the side ventilation holes in the stator.

<u>Measured Alignment</u>: insert a steel scale through the ventilation slots in the cover of the stator and measure  $1-1/4 \pm 1/8$  inches from the stator (RT300S) cover to the outer face of the rotor.

- 6. DIN rail (35mm) mount the RT304C controller interface at a convenient location. **CAUTION: To promote airflow and prevent overheating, the RT304C must have at least 1-inch clearance above and below the enclosure.**
- Connect one end of the provided coax cable to the BNC plug on the RT300S stationary housing and the other end to the BNC plug on the RT304C.
- 8. Connect a power source to the proper terminals indicated on the RT304C. Acceptable power is 22-35VDC or 17-27VAC. CAUTION: Power source must be isolated from current output.
- 9. Connect the 4-20 mA current loop (from the customer's process controller) to the current source terminals indicated on the RT304C.
- 10. Allow a 30 second start up.



Installation Diagram



Rotor/RTD Connections

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## **Troubleshooting**

In normal operating mode the Power status light, the Data status light and the CH status light are all on solid. In error mode, one or more of the LED's on the RT304C Controller Interface will flash <u>and a high temperature signal</u> (approximately 24 mA) will be output. Refer to the table below when troubleshooting an error mode event.

<del>1-1-1</del>	<del></del>
Power Status On solid Flash fast (5Hz)	<u>Condition</u> Stator and rotary power in spec Rotary power out of spec
Flash slow (2Hz) Off	Stationary power out of spec System not powered
10 sec on/1 sec off [Data light off, RTD	Insufficient rotary power or data not received (Rotor Reset mode)

[Data light off, RTD not received (Rotor Reset mode) light(s) blinking]

Data StatusConditionOn solidDigital transmission is error-freeFlickeringIntermittent transmission errors

Off Data not received

Ch 1 StatusConditionOn solidNo errors detectedFlash fast (5Hz)Rotary side error:<br/>RTD out of range (including

open or shorted)

Flash slow (2Hz) Open circuit in 4-20mA loop

**Corrective Action** 

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Check rotor/stator spacing, and coaxial connections Check power source Check power source, and power connections Check rotor/stator spacing, and coaxial connections

**Corrective Action** 

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Check rotor/stator spacing, coax connections

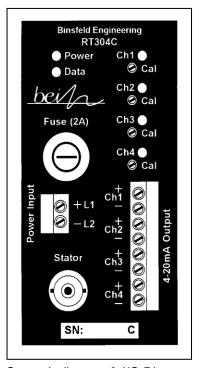
Check rotor/stator spacing, and coaxial connections

**Corrective Action** 

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Check RTD, connections

Check connections and continuity of current loop



Status Indicators & I/O Diagram

If the status lights do not agree with conditions listed above, remove power to the RT304C for 5 seconds, and then restore power (to reset the digital circuitry). Go to <a href="http://www.binsfeld.com/temptrak/rt300/">http://www.binsfeld.com/temptrak/rt300/</a> for more trouble shooting aids.

### **Specifications**

Rotor: Number of sensors 1-4

Sensor connection: #4-40 screw terminals with socket-head cap screws

Input sensor type: Non-standard RTD (133.65  $\Omega$  at 0°C)

Sensor range:  $0 - 200^{\circ}$  C Speed: 10,000 RPM

Stator: Connector: Coaxial interconnect (BNC)

Controller Output connection: Quick connect screw terminal block. Interface: Output signal: 4-20 mA (Linear with 0 - 200° C)

Power input: 22-35 VDC or 17-27 VAC; 2A max, 0.5A nominal

Max load resistance 400  $\Omega$ 

General: Accuracy (typical error): ±0.30% span over operating temperature range

Operating temperature: 0 - 100° C

Humidity: 0-90% RH, non-condensing

This document is subject to change without prior notification.

### Warrantv

Binsfeld Engineering Inc. warrants this product to be free from defective materials and workmanship for a period of five years from the date of delivery to the original purchaser and that this product will conform to specifications and standards published by Binsfeld Engineering Inc. Upon evaluation by Binsfeld Engineering Inc., any product found to be defective will be replaced or repaired at the sole discretion of Binsfeld Engineering Inc. Our warranty is limited to the foregoing. Binsfeld Engineering Inc. disclaims any warranty of merchantability or fitness for intended purpose.