RT303 Rotary Temperature Transmitter (850-303)

The RT303 rotary temperature transmitter is a digital system designed to accurately transmit temperature data from RTD sensors embedded in the heated godet roll shell. The system consists of three components: The RT303R rotary assembly, the RT300S stationary assembly and the RT303C controller interface assembly.





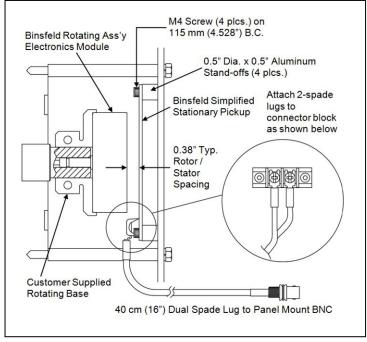


Installation

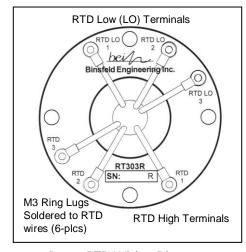
- Secure the RT303R transmitter module (provided) to the rotating base using button head cap screws with thread-locking adhesive (Loctite 222MS or equivalent).
- 2. Slide the RT303R rotary assembly onto shaft with steel base toward motor. Secure the base to the shaft by tightening the compression screws (alternating from one screw to the other).

Note: The RT303R requires proper positioning on the shaft; see Step 7 for details.

- Review the drawing (lower right) for wiring the RTD connections onto the RT303R rotary assembly.
 Secure leads with the M3 socket head cap screws provided
- 4. **IMPORTANT!** Pull excess RTD leads towards the front of the godet roll to be stored under the godet cover. This prevents lead wires from rubbing against the RT300S stationary board during rotation.
- Secure the RT300S stationary assembly to the cross brace using M4 bolts (provided) and 4 standoffs (provided) with thread-locking adhesive (Loctite 222MS or equivalent).
- 6. Insert the 40 cm coax adapter cable, spade lugs first, into the motor back-plane and thread the BNC connector in place. Install the lock washer and jam nut on the back of the connector. Feed the spade lug end of the cable through the 6 mm hole in the fan housing and connect the spade lugs to the terminal strip on the RT300S stationary assembly (polarity not important).
- 7. Reinstall the cross brace. Verify that the rotor to stator spacing is approximately 10 mm (0.38 inches).
- 8. DIN rail (35mm) mount the RT303C controller interface at a convenient location. CAUTION: To promote airflow and prevent overheating, the RT303C must have at least 25 mm clearance above and below the enclosure.
- 9. Connect one end of the 75 ft. interconnect cable to the BNC bulkhead connector on the adapter cable (installed in motor backplane) and the other end to the BNC plug on the RT303C.
- 10. Connect a power source to the proper terminals indicated on the RT303C. Acceptable power is 22-35VDC or 17-27VAC. **CAUTION: Power source must be isolated from current output.**
- 11. Connect the 4-20 mA current loops (from the customer's process controller) to the current source terminals indicated on the RT303C.
- 12. Allow a 30 second start up.



Installation Diagram



Rotor-RTD Wiring Diagram

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Troubleshooting

In normal operating mode the Power status light, the Data status light and the CH status light are all on solid. In error mode, one or more of the LED's on the RT303C Controller Interface will flash and a high temperature signal (approximately 24 mA) will be output. Refer to the table below when troubleshooting an error mode event.

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Power Status On solid Flash fast (5Hz)	<u>Condition</u> Stator & rotor power in spec Rotary power out of spec
Flash slow (2Hz) Off	Stationary power out of spec System not powered
10 sec on/1 sec off [Data light off, RTD light(s) blinking]	Insufficient rotary power or data not received (Rotor Reset mode)

Condition **Data Status**

On solid Digital transmission is error-free Intermittent transmission errors Flickering

Off Data not received

Ch 1 Status **Condition** On solid No errors detected Rotary side error: Flash fast (5Hz)

RTD out of range (including

open or shorted)

Flash slow (2Hz) Open circuit in 4-20mA loop

continuity of current loop

Corrective Action

Check rotor/stator spacing, and coaxial connections Check power source Check power source, and power connections Check rotor/stator spacing, and coaxial connections

Corrective Action

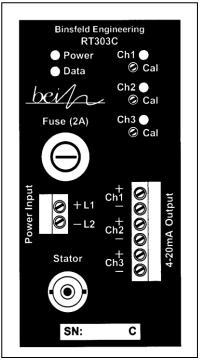
Check rotor/stator spacing,

coax connections Check rotor/stator spacing, and coaxial connections

Corrective Action

Check RTD, connections

Check connections and



Status Indicators & I/O Diagram

If the status lights do not agree with conditions listed above, remove power to the RT301C for 5 seconds, and then restore power (to reset the digital circuitry). Go to http://www.binsfeld.com/temptrak/rt300/ for more trouble shooting aids.

Specifications

Rotor: Number of sensors 1-3

> Sensor connection: M3-0.5 screw terminals with socket-head cap screws PT100 RTD (100 Ω at 0° C, α =.00385, two wire) Input sensor type:

0 - 300° C Sensor range: Speed: 10,000 RPM

Connector: Stator: 40 cm (16"); Spade lugs to BNC Bulkhead Connector

Controller Output connection: Quick connect screw terminal block. Interface: Output signal: 4-20 mA (Linear with 0 - 300° C)

> 22-35 VDC or 17-27 VAC; 2A max, 0.5A nominal Power input:

Max load resistance 400 Ω

Accuracy (typical error): ±0.30% span over operating temperature range General:

Operating temperature: 0 – 100° C

Humidity: 0 - 90% RH, non-condensing

This document is subject to change without prior notification.

Warrantv

Binsfeld Engineering Inc. warrants this product to be free from defective materials and workmanship for a period of five years from the date of delivery to the original purchaser and that this product will conform to specifications and standards published by Binsfeld Engineering Inc. Upon evaluation by Binsfeld Engineering Inc., any product found to be defective will be replaced or repaired at the sole discretion of Binsfeld Engineering Inc. Our warranty is limited to the foregoing. Binsfeld Engineering Inc. disclaims any warranty of merchantability or fitness for intended purpose.