RT302 Rotary Temperature Transmitter (850-302)

The RT302 rotary temperature transmitter is a digital system designed to accurately transmit temperature data from RTD sensors embedded in a heated godet roll shell. The system consists of three components: The RT302R rotary assembly, the RT300S stationary assembly, and the RT302C controller interface assembly.







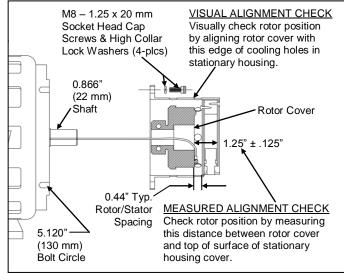
Installation

- Slide the RT302R rotary assembly onto shaft with steel base toward motor. Tighten the (2) 1/4-20 compression screws (alternating from one screw to the other) to lock assembly onto shaft.
 - Note: The RT302R requires proper positioning on the shaft; see Step 5 below for details.
- 2. Secure RTD leads with the 4-40 x 1/4" socket head cap screws provided (see Rotor-RTD Wiring Diagram).
- 3. **IMPORTANT!** Pull excess RTD leads towards the front of the godet roll to be stored under the godet cover. This prevents lead wires from rubbing against inside cover of RT300S stationary housing during rotation.
- Carefully position the RT300S stationary housing over shaft-mounted RT302R transmitter and mount it to the motor using (4) M8-1.25 x 20mm long socket head cap screws and lock washers provided.
- 5. **IMPORTANT!** Refer to the Installation Diagram to verify correct axial spacing between rotor and stator using either of the following methods:

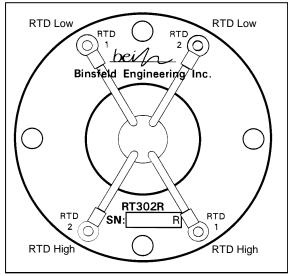
<u>Visual Alignment</u>: sight the outer face of the rotor through the side ventilation holes in the stator.

<u>Measured Alignment</u>: insert a steel scale through the ventilation slots in the cover of the stator and measure 1-1/4 \pm 1/8 inches from the stator (RT300S) cover to the outer face of the rotor.

- DIN rail (35mm) mount the RT302C current controller interface at a convenient location. CAUTION: To promote airflow and prevent overheating, the RT302C must have at least 1-inch clearance above and below the enclosure.
- Connect one end of the provided coax cable to the BNC plug on the RT300S stationary housing and the other end to the BNC plug on the RT302C.
- Connect a power source to the proper terminals indicated on the RT302C. Acceptable power is 22-35VDC or 17-27VAC.
 CAUTION: Power source must be isolated from current output
- Connect the 4-20mA current loop (from the customer's process controller) to the current source terminals indicated on the RT302C.
- 10. Allow 30 seconds for start up.



Installation Diagram



Rotor-RTD Wiring Diagram

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Troubleshooting

In normal operating mode the Power status light, the Data status light and the Channel (Ch) status light are all on solid. In error mode, one or more of the lights on the RT302C Controller Interface will flash and a high temperature signal (approximately 24 mA) will be output. Refer to the table below when troubleshooting an error mode event.

tapproximately 24 mA) will be output. There to the tab	
Power Status On solid Flash fast (5Hz)	Condition Stator & rotor power in spec Rotary power out of spec
Flash slow (2Hz) Off	Stationary power out of spec System not powered
10 sec on/1 sec of [Data light off, RTE light(s) blinking]	, , , , , , , , , , , , , , , , , , ,

Data Status Condition

Digital transmission is error-free On solid Flickering Intermittent transmission errors

Off Data not received

Ch 1 - 2 Status Condition

No errors detected On solid Flash fast (5Hz) Rotary side error:

RTD out of range (including

open or shorted)

Open circuit in 4-20mA loop Flash slow (2Hz)

continuity of current loop

Corrective Action

Check rotor/stator spacing, and coaxial connections Check power source Check power source, and power connections Check rotor/stator spacing, and coaxial connections

Corrective Action

mode)

Check rotor/stator spacing, and coaxial connections Check rotor/stator spacing, and coaxial connections

Corrective Action

Check RTD, connections

Check connections and

Binsfeld Engineering RT302C Ch2 Fuse (2A)

Status Indicators & I/O Diagram

If the status lights do not agree with conditions listed above, remove power to the RT302C for 5 seconds, and then restore power (to reset the digital circuitry). Go to http://www.binsfeld.com/temptrak/rt300/ for more trouble shooting aids.

Specifications

Rotor: Number of sensors: 1 - 2

> Sensor connection: #4-40 screw terminals with socket-head cap screws Input sensor type: PT2000 RTD (2000 Ω at 0°C, α = .00385, two wire)

Sensor range: $0 - 300^{\circ} C$ Speed: 10.000 RPM

Stator: Connector: Coaxial interconnect (BNC)

Controller Output connection: Quick connect screw terminal block. Interface: Output signal: 4-20 mA (Linear with 0° to 300° C)

> Power input: 22-35 VDC or 17-27 VAC, 2 A max, 1 A nominal

Max load resistance 400 Ω

General: Accuracy (typical error): ±0.30% span over operating temperature range

> Operating temperature: $0 - 100^{\circ} \dot{C}$

Humidity: 0 - 90% RH, non-condensing

This document is subject to change without prior notification.

Warranty

Binsfeld Engineering Inc. warrants this product to be free from defective materials and workmanship for a period of five years from the date of delivery to the original purchaser and that this product will conform to specifications and standards published by Binsfeld Engineering Inc. Upon evaluation by Binsfeld Engineering Inc., any product found to be defective will be replaced or repaired at the sole discretion of Binsfeld Engineering Inc. Our warranty is limited to the foregoing. Binsfeld Engineering Inc. disclaims any warranty of merchantability or fitness for intended purpose.